

PATENT

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APPLICATION FOR UNITED STATES LETTERS PATENT

for

CONDUCTOR TORQUING SYSTEM

by

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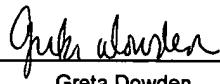
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1 This application is a CIP of US Application Serial No. 10/367,210, filed February
2 14, 2003, the entire contents of which are incorporated herein, which claims the benefit
3 of British Application No. GB 0206348.5, filed March 18, 2002.

FIELD OF THE INVENTION

5 This invention relates to drilling equipment useful in the oil and gas industry. In
6 particular, a system and method for making up or breaking out large diameter conductor
7 casing or piles with threaded connectors in a vertical or horizontal mode are disclosed.

BACKGROUND OF THE INVENTION

10 Large diameter threaded conductor casings and piles are commonly used in
11 drilling wells in the oil and gas industry, particularly for offshore wells. Typical
12 conductor casing sizes used in the oil and gas industry range from 16 inches to 48 inches
13 in diameter. Large diameter threaded tubulars are also used as pilings to secure offshore
14 structures to the seafloor. These pilings may range from 16 inches to 48 inches and
15 larger in diameter. These tubulars typically come in joints that are 30 to 40 feet in length
16 with a threaded pin member on one end and a threaded box member on the other end.

17 Make-up of such large diameter threaded conductor casings typically requires
18 rotating an upper joint so that its threaded pin member can screw into and make-up with
19 the threaded box member of a stationary joint located in the rotary table. Currently, most
20 conductor make-up service companies use rope to rotate or spin the upper joint of casing
21 to partially make-up the connection. Two manual rig tongs are then connected to the two
22 joints of conductor pipe, one above and one below the threaded connection, to torque the
23 connection to the final make-up value. Other conductor make-up service companies may
24 use a power tong to rotate or spin the upper joint of casing to make-up the connection. A

1 separate manual tong is used on the bottom joint of casing to provide backup support to
2 prevent the lower joint from rotating relative to the first joint of casing.

3 The current method of making up large diameter threaded connections is a
4 hazardous process at best, involving several pieces of large, cumbersome equipment and
5 several personnel working on the rig floor. There are safety hazards with the use of a
6 rope for spinning pipe and in the handling and manipulation of both manual and powered
7 tongs.

8 Thus, there is a need for a system and method of making up, or breaking out,
9 large diameter threaded conductor casing which reduce the potential for injury to the
10 operator and equipment and to create a more cost effective, efficient operation. The
11 present invention is directed to a system and method which addresses this need for
12 running large diameter threaded casings and/or piles. The invention also has application
13 in the make-up or break-out of large diameter threaded tubulars in the horizontal mode,
14 such as the laying of new pipeline.

15

16 **SUMMARY OF THE INVENTION**

17 In one embodiment of the invention, an apparatus for making up large diameter
18 conductor casing having threaded connections is provided which comprises a lower chain
19 vise adapted to grip a first joint of conductor casing to prevent rotation thereof, a plurality
20 of moveable arms operable to apply a retaining force to a second joint of conductor
21 casing to maintain a second joint of conductor casing in rotational contact with one or
22 more drive wheels on a spinner means. The spinner means is operable to rotationally
23 make-up a threaded connection for connecting the second joint of conductor casing to the
24 first joint of conductor casing to an initial make-up torque. The apparatus also includes

1 an upper chain vise adapted to grip the second joint of conductor casing and operable to
2 apply a final make-up torque to the threaded connection connecting the second joint of
3 conductor casing to the first joint of conductor casing. In one embodiment, the upper
4 chain vise includes a pair of chains latchable together to grip the second joint of
5 conductor casing, wherein the end of one of the chains is attached to a chain tensioner
6 cylinder operable to tension the chains and the other end is attached to an anchor means.
7 Similarly, the lower chain vise includes a pair of chains latchable together to grip the first
8 joint of conductor casing wherein the end of one of the chains is attached to a chain
9 tensioner cylinder that is operable to tension the chains and the other end is attached to an
10 anchor means. A wrenching cylinder may connect the upper and lower chain vises
11 wherein operation of the wrenching cylinder transmits the final makeup torque to the
12 upper chain vise. The upper chain vise and lower chain vise may include one or more die
13 blocks for gripping the conductor casing. A drive arm cylinder may be used to actuate
14 the movable arms. Preferably, the chain tensioner, wrenching, and drive arm cylinders,
15 as well as the drive unit for the drive wheels, are hydraulically actuated. Another
16 embodiment of the apparatus includes pivotable support arms for supporting the pair of
17 chains for the upper chain vise, wherein the support arms are movable between a first
18 position where the chains may be latched together and a second position where the chains
19 may be released from the second joint of conductor casing. Similarly, the pair of chains
20 for the lower chain vise may be supported by pivotable support arms, wherein the support
21 arms are moveable between a first position where the chains may be latched together and
22 a second position where the chains are released from the first joint of conductor casing.
23 The apparatus may have one or more movable arms operable to apply a retaining force to

1 the second joint of pipe to maintain the second joint of pipe in rotational contact with the
2 drive wheels of the spinner means.

3 Another embodiment of the invention is directed to an apparatus for making up
4 jointed pipe with threaded connections comprising a first chain vise adapted to grip a first
5 joint of pipe to prevent rotation thereof, a spinner means having one or more drive wheels
6 operable to rotationally make-up a threaded connection for connecting a second joint of
7 pipe to the first joint of pipe to an initial make-up torque, and a second chain vise adapted
8 to grip the second joint of pipe and operable to apply a final make-up torque to the
9 threaded connection. The lower and upper chain vises may each include a pair of chains
10 latchable together to grip the first and second joints of pipe respectively. Pivotal
11 support arms for supporting the respective pair of chains may also be included wherein
12 the support arms are movable between a first position where the chains may be latched
13 together and a second position wherein the chains are released from the first joint and
14 second joint of pipe, respectively.

15 An additional embodiment involves the use of high tensile webbing straps instead
16 of chains to form “grip heads” as opposed to “chain vises.” A grip head utilizes two
17 webbing straps made of materials that are able to withstand an upper torque range of
18 about 150,000 ft. pounds. An upper grip head, also known as the rotary grip head, and
19 the lower grip head, also known as the fixed grip head, may be present on the apparatus.
20 Each grip head may contain two arms that wrap around the casing. In one particular
21 embodiment, the rotary grip head includes a pair of straps latchable to a grip head
22 housing and used to grip the second joint of conductor casing. One end of the strap is

1 attached to a strap tensioner cylinder and the other to the fixed strap adjustment
2 assembly.

3 According to another embodiment of the invention, a method for making up large
4 diameter conductor casing having threaded connections is provided which includes the
5 steps of gripping a first joint of conductor casing with a lower chain vise to prevent
6 rotation thereof, applying a retaining force to a second joint of conductor casing with one
7 or more arms to maintain the second joint of conductor casing in rotational contact with
8 one or more drive wheels on a spinner means, making up a threaded connection
9 connecting the second joint of conductor casing to the first joint of conductor casing to an
10 initial make-up torque with the spinner means and applying a final make-up torque to the
11 threaded connection connecting the second joint of conductor casing to the first joint of
12 conductor casing with an upper chain vise.

13 According to another embodiment of the invention, a method for breaking out
14 jointed pipe having threaded connections is disclosed. The method comprises the steps of
15 gripping a first joint of pipe with a lower chain vise to prevent rotation thereof, applying
16 a retaining force to a second joint of pipe with one or more arms to maintain the second
17 joint of pipe in contact with one or more drive wheels on a spinner means, applying a
18 breakout torque to the threaded connection connecting the second joint of pipe to the first
19 joint of pipe with an upper chain vise, and breaking out the threaded connection with the
20 spinner means until the second joint of pipe is disconnected from the first joint of pipe,
21 wherein the lower chain vise, the upper chain vise, the one or more arms and the spinner
22 means are components of a single apparatus.

1 Another embodiment of the invention involves a method for making up large
2 diameter conductor casing having threaded connections is provided which includes the
3 steps of gripping a first joint of conductor casing with a fixed grip head to prevent
4 rotation thereof, applying a retaining force to a second joint of conductor casing with one
5 or more arms to maintain the second joint of conductor casing in rotational contact with
6 one or more drive wheels on a spinner means, making up a threaded connection
7 connecting the second joint of conductor casing to the first joint of conductor casing to an
8 initial make-up torque with the spinner means and applying a final make-up torque to the
9 threaded connection connecting the second joint of conductor casing to the first joint of
10 conductor casing with a rotary grip head. As similar method for breaking out jointed pipe
11 may be accomplished by the present invention.

12 According to an additional embodiment of the present invention, a method for
13 making up jointed pipe having threaded connections is disclosed. The first joint of pipe
14 is gripped by a gripping means to prevent rotation. A second joint of pipe is retained
15 against one or more drive wheels on a spinner means. The threaded connection between
16 the first joint and second joint of pipe is made-up to an initial torque using the spinner
17 means. A final torque to the threaded connection is applied by a gripping means on the
18 second joint of pipe.

19 An additional embodiment of the present invention involves an automated
20 apparatus for making up and breaking out jointed pipe. The apparatus comprises a rotary
21 grip head, a fixed grip head, arms, and a spinner means. As the apparatus is moved into
22 position around the pipe, the arms are retracted around the casing, thereby placing
23 webbing in contact with the casing. The webbing is attached to the outer and inner arm

latches, which come together around the pipe and are held in place by a latch pin. After tensioning the webbing, the spinner means is used to apply torque to the pipe. After final torque is applied to the pipe using the rotary grip head, the webbing tension is released, the latch pin is removed, and the arms swing open allowing the apparatus to be moved away from the pipe.

BRIEF DESCRIPTION OF THE DRAWINGS

The following figures form part of the present specification and are included to further demonstrate certain aspects of the present invention. The invention may be better understood by reference to one or more of these figures in combination with the detailed description of the specific embodiments presented herein. Figure 1 is a side view of the conductor torquing apparatus according to one embodiment of the present invention.

Figure 2 is a sectional plan view showing the conductor torquing apparatus with the retaining arms in the open position.

Figure 3 is a sectional plan view showing the apparatus of Figure 2 making up a smaller diameter conductor casing with the retaining arms in the closed position.

Figure 4 is a sectional plan view illustrating a chain vise with support arms.

Figure 5 is an end view of the upper and lower chain vises and wrenching cylinder.

Figure 6 is a side view of an embodiment of the invention in horizontal operation on a large diameter threaded tubular.

Figure 7 is an overhead view of the conductor torquing apparatus according to one embodiment of the present invention.

Figure 8 is a sectional view of the fixed grip head with the arms in a closed position.

1 Figure 9 is a sectional view of the rotary grip head with the arms in a closed
2 position.

3 Figure 10 is a section view of the fixed grip head with a cover plate in position.

4 Figure 11 is a side view of the inner latch arm and latch mechanism showing the
5 installation of the latch pin.

6 Figure 12 is a side view of the conductor torquing apparatus according to one
7 embodiment of the present invention.

8 Figure 13A is an overhead view of the webbing straps.

9 Figure 13B is a side view of the webbing straps.

10 Figure 14 is a simplified view of the latching mechanism.

11 Figure 15 is an overview of the cross-sections of the latching mechanism.

12 Figure 16 is a cross-section of the latch cylinder guide rod.

13 Figure 17 is a cross-section of the latch pin and latch cylinder.

14 Figure 18 is a cross-section of the outer latch strap pin.

15 Figure 19 is a side view of the inner latch arm pivot.

16 Figure 20 is a cross-section of the installed latch pin.

17

18 **DESCRIPTION OF ILLUSTRATIVE EMBODIMENTS**

19 The following examples are included to demonstrate preferred embodiments of
20 the invention. It should be appreciated by those of skill in the art that the techniques
21 disclosed in the examples which follow represent techniques discovered by the inventors
22 to function well in the practice of the invention, and thus can be considered to constitute
23 preferred modes for its practice. However, those of skill in the art should, in light of the
24 present disclosure, appreciate that many changes can be made in the specific

1 embodiments which are disclosed and still obtain a like or similar result without
2 departing from the spirit and scope of the invention.

3 Referring to Figure 1, the conductor torquing apparatus of the present invention is
4 shown making up a large diameter threaded conductor casing. More particularly,
5 conductor torquing apparatus 10 is making up an upper conductor casing joint 1 to a
6 lower conductor casing joint 2. The upper and lower joints of conductor casing are
7 connected by a conventional large diameter threaded connection 3, typically including a
8 threaded pin member (not shown) on the bottom of upper joint 1 which will stab into and
9 make-up with a box member (not shown) on lower conductor casing joint 2 having
10 mating threads. Traditional sizes for large diameter conductor pipe used in the offshore
11 energy industry include 16", 18 5/8", 20", 24", 26", 30", 36", 42" and 48" diameters.
12 Although the present invention is particularly suited to make-up or break-out such
13 traditional large diameter threaded conductor casings, one of skill in the art will
14 appreciate that the invention could be modified to handle smaller diameter threaded
15 tubulars as well.

16 The conductor torquing apparatus 10 includes a support frame 15 with eyelet 18
17 on its uppermost end. Apparatus 10 may be suspended from the derrick or from a
18 commercially available automated mechanism for maneuvering power tongs to and from
19 the well center line during casing running operations, such as BJ Tubular Services'
20 Leadhand MKII. Cables and/or chains for suspending the conductor torquing apparatus
21 from the derrick or automated mechanized system may be attached to eyelet 18.

22 Attached to the lower end of support frame 15 is lower chain vise 20 which is
23 adapted to grip the upper portion of lower conductor casing 2 that extends from the rotary

1 table. Lower chain vise 20 includes chain 22 which wraps around, and ultimately grips,
2 the lower conductor casing. Chain 22 may consist of two separate lengths which have a
3 latching device 29 to connect the two lengths of the chain about the conductor casing.
4 Alternatively, a full wrap of chain may extend substantially around the conductor casing
5 and attaches using any conventional latching device, such as a "cocks comb" or
6 removable pin. Such latching devices are well known in the art. Lower chain vise 20
7 may also include chain tensioner cylinder 60 which is attached to one end of chain 22 as
8 shown in Figures 2 and 4. The other end of chain 22 may be secured by any suitable
9 anchor means such as pin 23. To facilitate handling of chain 22, chain vise 20 may
10 include support arms 24, which may be pivotably attached to horizontal support member
11 26. Handles 27 may be used to open, connect and disconnect chain 22 about casing 2.

12 Chain tension cylinder 60, when actuated, will apply sufficient tension on chain
13 22 to prevent lower conductor casing 2 from rotating. Chain vise 20 may include one or
14 more die blocks 31 for applying an additional gripping force on casing 2 when chain 22 is
15 tensioned. Die blocks 31 are similar to conventional tong dies and include teeth for
16 biting into the casing. Once chain 22 is fully tensioned, lower chain vise 20 serves as an
17 anchor for apparatus 10. Lower chain vise 20 also provides backup support to prevent
18 lower conductor casing 2 from rotating during the rotational make-up of upper conductor
19 casing 1 to the lower conductor casing.

20 Upper chain vise 30 is spaced vertically above lower chain vise 20 as shown in
21 Figure 1. Upper chain vise 30 is adapted to grip the upper conductor casing 1 and is
22 operable to apply a final make-up torque to the threaded connection 3 as described in
23 more detail below. Upper chain vise 30 is similar in construction and operation to lower

1 chain vise 20 with chain 32 being of sufficient length to extend around the upper
2 conductor casing. Chain 32 attaches to a separate chain tensioner cylinder 60 on one end
3 and to an anchor means, such as pin 23, on the other end. Chain tensioner cylinders 60
4 are preferably hydraulically actuated, although the apparatus could be actuated by
5 electromechanical or pneumatic means. Chain 32 may be latched in a similar fashion as
6 chain 22, such as by a latching device similar to latching device 29. Upper chain vise 30
7 may also include one or more die blocks, similar to die blocks 31, to further grip upper
8 conductor casing 1 when final makeup is applied by the upper chain vise. The die blocks
9 may be positioned about the horizontal support members (member 26 and a comparable
10 member on the upper chain vise) to grip a range of pipe diameters. By way of example,
11 the die blocks may be positioned to grip conductor casings ranging from 16" to 48".

12 Supports 38 provide additional vertical supports and spacing between upper chain
13 vise 30 and lower chain vise 20. The supports 38 needs to be of sufficient length to
14 ensure that upper chain vise 30 will grip the upper conductor casing joint after lower
15 chain vise 20 has gripped the lower conductor casing joint. The threaded connectors may
16 have upset box and pin members which have a greater outer diameter than the conductor
17 casing itself. The upper and lower chain vises for conductor torquing apparatus 10 can
18 easily accommodate the larger diameter box and pin members. Thus, it shall be
19 understood that references to gripping the upper or lower conductor casing joints with the
20 chain vise is meant to include the gripping of the box and/or pin members of the threaded
21 connector as well.

22 A spinning means is attached to support frame 15 above the upper chain vise 30.
23 Spinning means 65 may include one or more drive wheels 68, and a spinning section

1 drive gear unit 70 for each drive wheel. In another preferred embodiment, spinning
2 means 65 also includes retaining arms 50 and arm drive cylinder 65. Referring to Figure
3 2, movable retaining arms 50 are shown in the open position about the upper conductor
4 casing joint. Retaining arms 50 may be telescopic in nature to provide for greater
5 extension and/or to accommodate a wider range of conductor casing sizes. Arms 50 may
6 also include retaining rollers 55 attached to their distal ends. Retaining arms 50 are
7 attached to horizontal support frame 61 by pivot pins 58. Horizontal support frame 61
8 extends from support frame 15 and may be part of spinning means 65. The proximal end
9 of arms 50 is connected to drive cylinder 65 by any suitable connector such as pins 53.
10 Drive cylinder 65 may be positioned between the upper and lower plates of horizontal
11 support frame 61. Actuation of drive cylinder 65 will cause arms 50 to pivot about pivot
12 pins 58, thereby opening or closing arms 50 about a joint of conductor casing. Drive
13 cylinder 65 is illustrated in the extended position in Figure 3, wherein arms 50 are closed
14 about the upper conductor casing joint. Drive cylinder 65 is illustrated in the retracted
15 position in Figure 2 wherein arms 50 are moved to the open position.

16 In the closed position, arms 50 apply a retaining force to the upper joint of
17 conductor casing to maintain the joint in rotational contact with drive wheels 68.
18 Although the embodiments shown in Figures 2 and 3 illustrate a pair of movable arms,
19 one of skill will appreciate that a single arm could be used so long as it applies a retaining
20 force to the upper joint of casing to maintain the joint in contact with drive wheels 68.

21 In one embodiment, drive wheels 68 have a polyurethane coating to maintain a
22 friction contact with the upper conductor casing joint during the initial rotational make-up
23 of the threaded connector 3. Alternatively, other suitable rubber materials may coat the

1 drive wheels. The drive wheels are driven by hydraulic motor gear box 70 which may be
2 attached to horizontal support frame 61. Retaining rollers 55 facilitate the rotation of
3 upper conductor casing joint 1. In a preferred embodiment, the spinning means includes
4 two drive wheels that are fixed in place but are capable of maintaining frictional contact
5 with a wide variety of different size conductor pipe. In a preferred embodiment, the
6 conductor torquing apparatus may make-up or break-out conductor pipe ranging from 16
7 inches up to 48 inches. As shown in Figures 2 and 3, horizontal support frame 61 may
8 have a V-shape to facilitate the handling of different size conductor casings. The spinner
9 means is used to rotate the upper joint of conductor pipe up to an initial make-up torque
10 value, for example, up to about 5000 foot pounds. The initial make-up torque may range
11 from stab-in to either shoulder engagement or achievement of taper thread interference,
12 depending upon the size, type and make of the threaded connector. In the initial make-up
13 position, threaded connector 3 will typically be within 15 degrees from a final make-up
14 position.

15 Once the spinner means has applied the initial make-up torque to the connection,
16 the upper chain vise 30 is used to apply the final make-up torque to the connection.
17 Chain 32 is tightened around the upper conductor casing joint by activating the chain
18 tensioner cylinder 60 for the upper chain vise. Once the upper chain vise has gripped the
19 upper conductor joint, wrenching cylinder 35 is actuated to apply the final make-up
20 torque to the connection. Wrenching cylinder 35 extends horizontally between the upper
21 and lower chain vises. A vertical boss 36 extends upwardly from the lower chain vise
22 and attaches to one end of wrenching cylinder 35. A downwardly extending boss 37
23 connects upper chain vise 30 to wrenching cylinder 35. The bosses 36 and 37 are

1 structurally mounted to transmit the load to each of the chain vises. To apply the final
2 make-up, wrenching cylinder 35 is retracted which causes chain 32 and upper conductor
3 casing 1 to rotate clockwise relative to lower chain vise 20 and lower casing conductor
4 joint 2. The rotation of chain 32 relative to lower chain vise 20 applies the necessary
5 torque across the threaded connection to reach the final make-up torque and position. In
6 one embodiment, the conductor torquing apparatus may be used to apply a final make-up
7 torque ranging from the initial make-up torque to about a 120,000 foot pounds.
8 However, it should be understood that the final make-up torque may vary depending
9 upon the size, type and make of the threaded connector.

10 In a preferred embodiment, the conductor torquing apparatus is hydraulically
11 operated. More particularly, chain tensioner cylinders 60, arm drive cylinder 65,
12 wrenching cylinder 35 and spinning means drive gear units 70 are hydraulically actuated.
13 However, one of skill in the art will appreciate that the apparatus could also be
14 electromechanically or pneumatically actuated. The apparatus may be operated by a
15 remote control console, thereby reducing the number of personnel on the rig floor. In a
16 preferred embodiment, a hydraulically actuated remote control unit is connected to
17 apparatus 10 and powered by any suitable commercial hydraulic power unit. It is
18 contemplated that a single operator could operate the conductor torquing apparatus from
19 the remote control unit located a sufficient distance away from the tubular make-up area
20 thereby reducing the potential for injury to the operator. In addition to being substantially
21 safer than conventional methods and apparatus for making-up and running (or breaking
22 out and retrieving) large diameter conductor casing, the present invention also is a more

1 cost effective and efficient way of making-up and running (or breaking-out and
2 retrieving) such conductor casing.

3 In another embodiment, illustrated in Figs. 8 and 12, a lower head grip, also
4 known as a fixed head grip 100 is attached to support 15 and is adapted to grip the upper
5 portion of lower conductor casing 2 that extends from the rotary table. Fixed head grip
6 100 includes two high tensile webbing straps 110 and 111 which wrap around, and
7 ultimately grip the lower conductor casing. The fixed head grip also includes a latching
8 mechanism that connects the straps so that the straps may be tensioned to grip the casing.
9 Inner latch arm strap 110 may consist of one continuous loop of webbing, wherein the
10 ends are joined together by stitching as shown in Figs. 13A and 13B to form several
11 loops that create layers of desired thickness. Perimeter bond stitching may also be
12 utilized to secure the loops of webbing together. Outer latch arm strap 111 may be made
13 in a similar manner. As shown in Fig. 9, one end of each strap 110, 111 may each be
14 secured to a strap tensioner cylinder 60, or a hand adjustment cylinder 62, while the other
15 end is attached to the inner 120 or outer 130 latch respectively. It is also possible for one
16 end of one strap to be attached to an anchor point, while the other end is attached to the
17 outer latch 120 or inner latch 130. It is also possible to attach one end of webbing strap
18 110 to a strap tensioner cylinder 60, and strap 111 to another strap tensioner cylinder 60,
19 while the other ends are attached to the inner 120 and outer 130 latch respectively. The
20 strap tensioner cylinder 60 is typically operated by hydraulics, and the hand adjustment
21 cylinder 62 may be used to adjust the anchor point for the webbing so that it may be used
22 with different casing sizes. An upper head grip, otherwise known as a rotary head grip
23 200, is attached around an upper conductor joint and has similar components.

1 The high tensile webbing straps as shown in Figs. 13A and 13B preferably are
2 made out of a material containing Kevlar, but other high tensile materials that will
3 withstand a torque of up to 150,000 ft. pounds may be used. In a preferred embodiment,
4 a typical width for the strap is about 8 inches and a typical thickness for the strap is about
5 $\frac{1}{4}$ (quarter) inch. Once the strap is stitched into a continuous loop, as depicted in Fig.
6 13A, the overall thickness in a preferred embodiment is approximately 6 inches. Only a
7 few different sizes of loops are needed because of the fixed strap adjustment assembly
8 62, the length of which may be adjusted to accommodate different diameter conductor
9 casing for a given length of strap. By way of example the hand wheel on adjustment
10 cylinder 62 may be turned to shorten or lengthen the telescopic arm of the cylinder. In a
11 preferred embodiment, only three strap loop sizes are necessary to handle casing sizes
12 that range from about 18 5/8" to about 24", about 26" to about 32", and about 34" to
13 about 37". All casing sizes in between may be gripped by adjusting one of the above
14 straps with the hand adjustment cylinder 62.

15 As shown in Figs. 8 and 11, two arms that may be attached to the support 15 (not
16 shown) by hydraulic cylinders 105 provide support for the webbing straps 110,111 when
17 they are not engaging the casing. Actuation of cylinders 105 will cause the arms to pivot
18 about pin 105A, thereby allowing the arms to open or close about the conductor casing.
19 Each arm may be made up of an inner arm 101 and an outer arm 102, with the inner arm
20 sliding longitudinally within the outer arm allowing adjustment for different casing sizes.
21 At the end of one arm is an inner latch assembly 120, and at the end of the other arm is an
22 outer latch assembly 130, attached such that the latch assemblies may pivot into position
23 around the conductor casing 2. A spring tension cylinder 106 may also be attached

1 between each arm and the latch assembly. This spring tension cylinder 106 causes the
2 inner and outer latch assemblies to pivot out of the way when the head grip assembly 100
3 is being maneuvered around the conductor casing 2. Once the inner latch 120 and outer
4 latch 130 assemblies come together, a latch pin 140 secures them such that when the
5 straps 110, 111 are tensioned, the conductor casing is securely held in place. Die blocks
6 31 may be included in support plate 26 to provide an additional gripping force on
7 conductor casing 2 to keep the casing from rotating during make-up of threaded
8 connector 3. The rotary grip head 200 grips the upper casing joint in substantially the
9 same way as the fixed grip head grips the lower casing joint.

10 An additional embodiment of the present invention involves an automated
11 apparatus for making up and breaking out jointed pipe. As shown if Figs. 7, 8, 9 and 12,
12 the apparatus 10 comprises a fixed grip head 100, a rotary grip head 200, and a spinner
13 means 65. Once an upper joint of casing 1 has been stabbed into the box end of the lower
14 joint 2 in the rotary table, the apparatus 10 is moved into position around the conductor
15 pipe. Arms 101,102 are positioned around the lower casing conductor 2, thereby placing
16 webbing 110,111 in contact with the outer diameter of the casing. The webbing 110,111
17 is attached to the inner arm 120 and outer arm 130 latches, which come together around
18 the casing. Inner latch hydraulic cylinder 107 and outer latch hydraulic cylinder 108
19 move the inner 120 and outer 130 latches into a closed position. After switch 152
20 indicates that the latches are properly aligned and together, a latch pin 140 is dropped into
21 place by hydraulic latch cylinder 144 to secure the inner 120 and outer 130 latches in a
22 closed position. The latch pin triggers switches 143 and 150. Switches 143 and 150 may
23 be cam operated valve switches or electric micro-switches. Switch 150 indicates that the

1 pin has been installed and that the webbing is ready to be tensioned. Hydraulic cylinder
2 60 is actuated to tension strap 111, and via inner and outer latches 120 and 130, strap 110.
3 Once tensioned, fixed grip head 100 prevents lower casing conductor 2 from rotating.

4 After tensioning the webbing 110,111, the spinner means 50 is used to rotate the
5 joint upper conductor to an initial make-up position as described in the previous
6 embodiment. Arms 201 and 202 of the rotary grip head 200 are then moved into position
7 around the upper joint 1. The webbing 210,211 attached to the outer 230 and inner 220
8 arm latches comes together around upper joint 1. The inner latch hydraulic cylinders 207
9 and the outer latch hydraulic cylinders 208 move the inner 220 and outer 230 latches
10 together into a closed position. After switch 252 indicates that the latches are properly
11 aligned and together, a latch pin 240 is dropped into place by a hydraulic latch cylinder to
12 secure the inner 220 and outer 230 latches in a closed position. The latch pin 240 triggers
13 position switches 243 and 250. Switch 250 indicates that the pin has been installed and
14 that the webbing is ready to be tensioned. Latch pin 240 and switches 243 and 250 are
15 not illustrated but are similar to latch pin 140 and switches 143 and 150.

16 After tensioning the webbing 210,211 using the tensioning cylinder 160, final
17 torque is applied to the pipe 1 by actuating a wrenching cylinder 35 as described above.
18 Actuation of the wrenching cylinder causes straps 210 and 211 and upper conductor
19 casing 1 to rotate clockwise relative to lower straps 110 and 111 and lower casing
20 conductor joint 2. After final torque has been applied (and the wrenching cylinder is
21 returned to its original position), the webbing tension is released using the tensioning
22 cylinder 160, and the latch pin 240 is removed. Switch 243 indicates that the pin has
23 been fully removed and actuation of inner latch cylinder 207 and outer latch cylinder 208

1 disconnect the inner and outer latches. Once the inner and outer latches, 220 and 230
2 respectively, are released, hydraulic cylinders 205 are retracted to swing arms 220 and
3 230 open. Similarly, after releasing tension on webbing straps 110, 111 using tensioning
4 cylinder 60, latch pin 140 is removed by stroking latching cylinder 144 to its extended
5 position. Switch 143 indicates that the pin has been fully removed, and latch cylinders
6 107 and 108 release the inner and outer latches 120 and 130. Hydraulic cylinders 105 are
7 actuated to open arms 120 and 130. Spinner arms 50 are also moved away from the
8 casing, allowing the apparatus 10 to be moved away from the completed connection 3.

9 A simplified version of a preferred embodiment of the latch mechanism of the
10 fixed grip head is shown in Fig. 14. Outer latch arm webbing 111 is attached to the outer
11 latch 130 via an outer latch strap pin 146. The outer latch 130 is pivotably attached to the
12 outer latch arm using an outer latch arm pin 148. The other latch 130 also comprises a
13 slot for a latch cylinder guide rod 142 to accommodate the latch pin 140. A latch
14 cylinder 144 is also attached to the outer latch 130 and operable to move the latch pin 140
15 between a latched and unlatched position. The inner latch arm webbing 110 is attached
16 to the inner latch 120 on a hollow cylinder 120A such that the latch pin 140 is dropped
17 into the cylinder when securing the inner latch 120 and outer latch 130 together. Fig. 15
18 shows an overview of the latch mechanism cross-sections further detailed in Figs. 16-20.
19 The latch mechanism for the rotary grip head is substantially the same.

20 Figure 16 shows a cross-section of the latch cylinder guide rod 142 in position
21 and engaging positioning switch 143. Latch cylinder guide rod 142 is connected to latch
22 cylinder 144 and latch pin 140 via latch pin plate 140A. Guide rod 142 serves as a guide
23 to help align latch pin 140 with hollow cylinder 120A when the latch pin is moved from

1 the unlatch to the latched positions by latched cylinder 144. Guide rod 142 is longer than
2 latch pin 140 and thus will enter into its mating receptacle prior to the entry of latch pin
3 140 into hollow cylinder 120A when moving from the unlatched to latched position. The
4 tapered end of guide rod 142 facilitates entry into its receptacle.

5 Fig. 17 depicts a cross-section of the latch pin 140 in position with the latch
6 cylinder 144 in the retracted position. Latch cylinder 144 may be hydraulically stroked to
7 lift latch pin 140 out of hollow cylinder 120A to release outer latch 130 from inner latch
8 120. Latch cylinder 144 is connected at its upper end to latch pin plate 140A and secured
9 at its lower end to outer latch 130 by bracket 144A.

10 Fig. 18 shows the detail of the outer latch strap pin 146 and the outer latch arm
11 pin 148. Outer latch 130 pivots about pin 148. Fig. 19 is a view of the inner latch arm
12 from the side and shows an arm pin 103 and the attachment point of the inner latch
13 hydraulic cylinder 107. Fig. 20 shows an installed latch pin 140 and latch pin plate 140A
14 engaging switch 150. For clarity purposes, hydraulic control lines for the embodiment
15 illustrated in Figs. 7-20 are not shown. However, the configuration and use of hydraulic
16 controls and the supporting lines are well known to one of skill in the art of automated rig
17 floor equipment. One of skill will also recognize that such hydraulic controls will allow
18 the operation of the conductor torquing apparatus from a remote location on the rig floor.
19 One of skill in the art will also recognize that the latching mechanism illustrated in Figs.
20 10 and 14-20 may also be used with the chain vise disclosed above.

21 In the preferred embodiment, the conductor torquing apparatus of the present
22 invention is hydraulically operated. However, one of skill will appreciate that the

1 apparatus may also be operated pneumatically, electrically or by a combination of such
2 systems.

3

4 The present invention also includes the methods of making-up threaded tubulars
5 using the previously described embodiments of the torquing apparatus. According to a
6 preferred method, a first joint of conductor casing is run into the wellbore and landed in
7 the rotary table. A new joint of conductor casing is picked up and moved in from the
8 rig's V-door. The second joint is positioned above and stabbed into the box member of
9 the joint of conductor casing suspended in the rotary table by using the rig's air tuggers or
10 by using an automated system. The conductor torquing apparatus 10 is moved
11 horizontally into engagement with the two joints of conductor casing, preferably by use
12 of the hydraulic arm of the BJ Tubular Services' Leadhand II system. The lower chain
13 vise 20 is closed about the lower casing conductor joint extending from the rotary table.
14 Lower chain tensioner cylinder 60 is actuated (i.e., retracted) to tension chain 22 thereby
15 locking the lower chain vise to conductor casing 2. Die blocks 31 may be included in
16 support plate 26 to provide an additional gripping force on conductor casing 2 to keep the
17 casing from rotating during make-up of threaded connector 3. Arms 50 are moved about
18 the upper joint of conductor casing, telescoping the arms outwardly if necessary as shown
19 in Figure 2. Arms 50 are closed about the conductor casing and retracted until the upper
20 joint of conductor casing is pressed firmly against drive wheels 68. The drive wheels are
21 rotated by drive unit 70 to rapidly rotate the upper joint of conductor casing at a low
22 torque to make-up threaded connector 3 to an initial make-up position. Arms 50 apply

1 sufficient horizontal force to ensure that the drive rollers are fully engaged on the upper
2 joint of conductor casing, and thereby have enough frictional force to rotate the joint.

3 Once the initial make-up torque is applied, the upper chain vise is actuated to grip
4 casing conductor 1 by applying tension to chain 32 by upper chain tensioner cylinder 60.
5 Thereafter, wrenching cylinder 35 is actuated (i.e., retracted) to apply rotational force to
6 the upper chain vise thereby causing the upper joint to rotate the final make-up distance
7 (e.g., about 1-3 radial inches) until the final make-up torque is applied to connector 3.

8 To release the conductor torquing apparatus, the tension is released from chain 32
9 by extending the upper chain tensioner cylinder 60. Drive cylinder 65 is contracted
10 thereby causing arms 50 to pivot about pivot pins 58 and move to the open position as
11 shown in Figure 2. Lower chain tensioner cylinders 60 is also extended to relieve the
12 tension on chain 22, after which chains 32 and 22 may be unlocked and apparatus 10 can
13 be pulled back away from the conductor casing.

14 The present invention additionally includes the methods of making-up threaded
15 tubulars using the previously described grip head embodiments of the torquing apparatus.
16 According to a preferred method, a first joint of conductor casing is run into the wellbore
17 and landed in the rotary table. A new joint of conductor casing is picked up and moved
18 in from the rig's V-door. The second joint is positioned above and stabbed into the box
19 member of the joint of conductor casing suspended in the rotary table by using the rig's
20 air tuggers or by using an automated system. The conductor torquing apparatus 10 is
21 moved horizontally into engagement with the two joints of conductor casing, preferably
22 by use of a hydraulic arm such as the BJ Tubular Services' Leadhand II system. The
23 fixed grip head 100 is closed about the lower casing conductor joint extending from the

1 rotary table. First, the inner latch arm will be rotated toward the casing until the inner
2 latch touches the casing. Next, the outer latch arm will swing around until it touches the
3 casing and the other latch contacts the inner latch, with cylinders 107 and 108 providing
4 the final movement into the latched position. An indicating switch 150 will indicate that
5 the connection has been properly made, and latch pin 140 will be hydraulically driven
6 into position by latch cylinder 144 to hold the inner and outer latch together and against
7 the casing. After switch 150 indicates that the latch pin 140 is in place, lower strap
8 tensioner cylinder 60 is actuated (i.e., retracted) to tension the straps 110, 111 thereby
9 locking the fixed grip head 100 to conductor casing 2. Die blocks 31 may be included in
10 support plate 26 to provide an additional gripping force on conductor casing 2 to keep the
11 casing from rotating during make-up of threaded connector 3.

12 Arms 50 are moved about the upper joint of conductor casing, telescoping the
13 arms outwardly if necessary as shown in Fig. 12. Arms 50 are closed about the conductor
14 casing and retracted until the upper joint of conductor casing is pressed firmly against
15 drive wheels 68. The drive wheels are rotated by drive unit 70 to rotate the upper joint of
16 conductor casing at a low torque to make-up threaded connector 3 to an initial make-up
17 position. Arms 50 apply sufficient horizontal force to ensure that the drive rollers are
18 fully engaged on the upper joint of conductor casing, and thereby have enough frictional
19 force to rotate the joint.

20 Once the initial make-up torque is applied, the rotary grip head is closed about
21 and actuated to grip casing conductor 1 by applying tension to straps 210, 211 with upper
22 strap tensioner cylinder 160. Thereafter, wrenching cylinder 35 is actuated (i.e.,
23 retracted) to apply rotational force to the rotary grip head thereby causing the upper joint

1 to rotate the final make-up distance (e.g., about 1-3 radial inches) until the final make-up
2 torque is applied to connector 3.

3 To release the conductor torquing apparatus, the tension is released from straps
4 210, 211 by extending the upper strap tensioner cylinder 160. Latch pin 240 is removed
5 by stroking latch cylinder 244 to its extended position (not shown). Switch 243 indicates
6 that the latch pin 240 has been removed, causing the outer latch arm 230 and the inner
7 latch arm 220 to swing open via the spring tension cylinder 206. Drive cylinder 65 is
8 contracted thereby causing arms 50 to pivot about pivot pins 58 and move to the open
9 position as shown in Fig. 7. Lower strap tensioner cylinder 60 is also extended to relieve
10 the tension on straps 110, 111, after which the latch pin 140 may be removed by
11 hydraulically extending latch cylinder 144. Switch 143 indicates that the latch pin is
12 fully retracted, causing the outer latch arm 130 and inner latch arm 120 to swing open via
13 the spring tension cylinder 106. Hydraulic cylinders 105 are retracted to pivot the outer
14 arms open and apparatus 10 can be pulled back away from the conductor casing.

15 One of skill in the art will realize that the above operations with the conductor
16 torquing apparatus, including the rotary 200 and fixed grip 100 heads may be
17 accomplished using a remote control console for hydraulic, pneumatic, and/or electric
18 control.

19 Although the above description has been directed to the make-up of a threaded
20 conductor casing connection, one of skill will appreciate that conductor torquing
21 apparatus 10 can be used to break-out a connection by reversing the operation of the tool.
22 More particularly, wrenching cylinder 35 may be actuated (i.e. extended) to cause upper
23 chain vise 30, or rotary grip head 200, to apply a counterclockwise rotation to the upper

1 conductor casing joint to break-out the connection. Drive wheels 68 may be rotated in
2 the opposite direction to unscrew the pin member on upper connector casing joint 1 from
3 the box member of lower conductor casing joint 2.

4 The torquing apparatus could also be used in making up or breaking out
5 horizontal pipe, such as laying pipelines which have threaded connectors. Figure 6
6 illustrates apparatus 10 rigged for use for horizontal operation. Frame 15 is folded at
7 joint 15a and secured by any suitable means as shown in Figure 6 so that torquing
8 apparatus 10 can make-up threaded connector 83 for joints 81 and 82 in essentially the
9 same manner as described for making-up conductor casing.

10 While the apparatus, compositions and methods of this invention have been
11 described in terms of preferred or illustrative embodiments, it will be apparent to those of
12 skill in the art that variations may be applied to the process described herein without
13 departing from the concept and scope of the invention. For example, in another
14 embodiment of the invention, drive wheels could be positioned on the distal end of arms
15 50, in place of retaining wheels 55. A separate drive unit would be associated with each
16 drive wheel. In an additional embodiment, the chains as a gripping means may be
17 replaced with webbing as shown in Fig. 12. The webbing straps 110,111 may be joined
18 together after being placed around the casing in a manner similar to the chain vise grip as
19 discussed above. One of skill in the art will realize that any method of securing the straps
20 to together so that they can withstand up to 150,000 ft lbs. of torque may be used. All
21 such similar substitutes and modifications apparent to those skilled in the art are deemed
22 to be within the scope and concept of the invention as it is set out in the following claims.